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ECC Cyber Emerging Tech Lab Smart Transportation

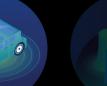
Smart Transportat



Scenario

Smart Buildings





Connected Products Critical Infrastructures



Smart Factories

Sma



3D representation of a connected car prototype

Focused on both understanding of internal flows of information and detection of anomalies originated by cyber threats. It includes: key Electronic Control Units (Powertrain, power management and body control) as well as relevant interactive systems (steering wheel, dashboard, infotainment and navigation system)

Connected vehicles are becoming on of the most trending topics of today for a large list of sectors and clients apart from vehicle vendors (assurance companies, OEMs, Transportation, fleets of vehicles, Smart cities, etc.).



Understanding Smart Transportation

A printed 3D prototype scratched from zero (3D design, electronics, mechanics and software) reproducing the main existent functionalities, systems and protocols in a connected car for its understanding, security assessment, improvement and development of security capabilities

Development of vSOC capabilities extracting and analyzing every single inCar event in real time, identifying anomalies and reacting against real threats

LCM (Light Control Module) / BMS (Battery Management System)

Power management, lights, and battery level. Implemented on an Arduino every + MCP2515 module for CAN bus connectivity.

Infotainment system / DM (Data Communication Module)

Management of wireless communications, navigation system and bridge between internal and external protocols (NFC, Bluetooth, Wi-Fi, GPS, etc.). Based on a Raspberry Pi and open car software. It's the entry point for multiple vector attacks (i.e. digital key, firmware updates, unlock doors, data privacy, etc.)

OBD-II-connector

AN hus

CAN bus

OBD-II-connector



BCM (Body Control Module)

Cabin control and management (belts, climate system, windows, door locks, crash detection, occupancy, etc.), airbags and car lock. Implementation on Arduino every + MCP2515 module for exchange of messages via CAN bus

PCM (Powertrain Control Module)

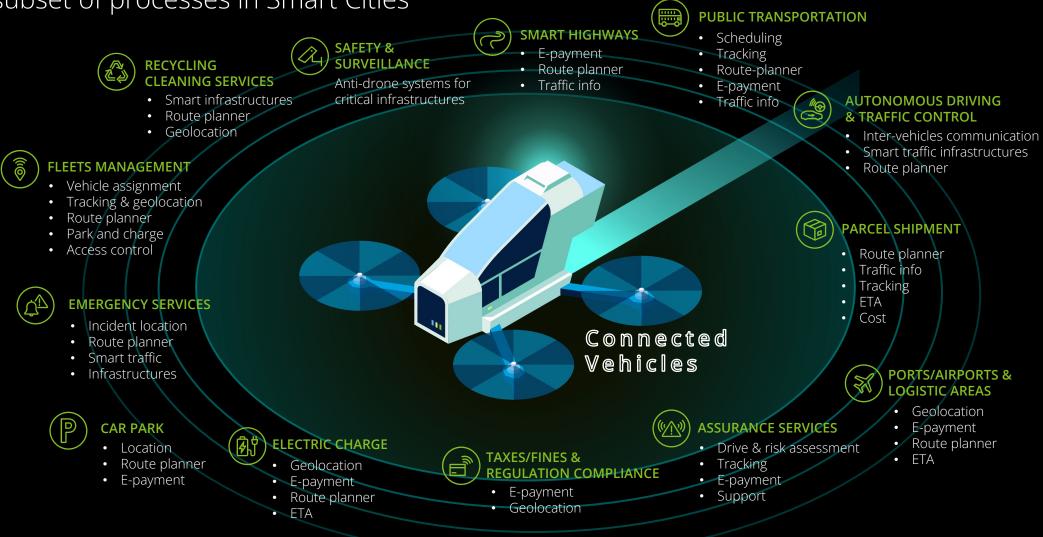
Unified transmission and driving control, including ABS, ESP and intelligent driving systems. Implemented on Arduino every + MCP2515 module, it receives orders and takes/communicates decisions via CAN bus (speed, slow down, direction, etc.), communicates with the engine subsystem thought LIN protocol managing temperatures, pressure, revolutions, and other parameters.

Steering controls

- 1. Wheel interface including acceleration, breaks, lights, Start/Stop, blinkers, direction, emergency, door lock, etc., based on Arduino Uno + MCP2515 module. It communicates with the rest of ECUS via CAN bus.
- 2. Dashboard representing in a graphical way the status of the main vehicle indicators (speed, revolutions, lights, power level, temperature, doors, errors, etc.) Based on Raspberry Pi + MCP2515 adapter it receives information from the rest of ECUS.

Smart Transportation

As a subset of processes in Smart Cities



Understanding Smart Transportation Capabilities and risks based on existent technologies

Connected vehicles are the **core component** of smart transportation processes

Complex and heterogeneous ecosystem based on multiple factors.



Type of vehicles: Cars, trucks, motorcycles, bikes, scooters, trains, plains, ships, drones...

Purpose: private use, public, passengers, parcels, surveillance, defense, etc.



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Engines: Manual, automatic or autonomous drive. Electric, hybrid, fuel powered, ...



Electronic systems & comms: ECUs, CANbus, ISO 9141, J1850, OBD2, LIN, TCP-IP, Wi-Fi, BLE, NFC, 4G, 5G, ...



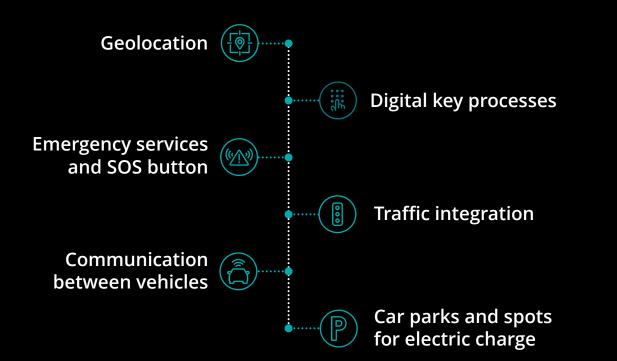
Vendors: ...

Understanding and assessing security at the vehicle level will reduce dramatically risks to smart transportation processes

Deployment of digital twins for the understanding and assessment of connected vehicles as a first step toward secure transportation process

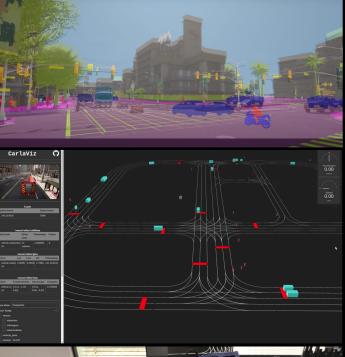
Understanding Smart Transportation Extending the digital twin to the Smart City ecosystem

Integration with CARLA as a parametrized virtual world Full analysis and assessment of **wireless communications and data flows:**











Cybersecurity for Smart Transportation Developing Cybersecurity capabilities

The understanding of smart infrastructures, services and protocols allow us to Identify new risks, to evaluate security solutions & to develop new effective security services:

Vehicle SOC

24x7 real time monitoring, identifying anomalies & threats against vehicles, discarding false positives & responding in the fastest way to reduce the impact of incidents & attacks

Smart Transportation Labs

A collaborative space between vendors & clients for the analysis & test of technologies, replicating complex infrastructures & processes through digital twins for the development of secure solutions



Smart Transportation / CP SOC*

24x7 real time integrated monitoring services for complex infrastructures combining IT, OT and IoT technologies addressed to detect and respond against Cyber Physical Security threats

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